

$\{X_n\}$  MC, initial dist is  $\alpha^T$  (dist of  $X_0$ ),  
transition matrix  $P$

$\Downarrow$

dist of  $X_n$ :  $\alpha^T \cdot P^n$

$\Downarrow$

limiting dist is  $\lim_{n \rightarrow \infty} \alpha^T \cdot P^n$

$$\parallel \\ \alpha^T \cdot \boxed{\lim_{n \rightarrow \infty} P^n}$$

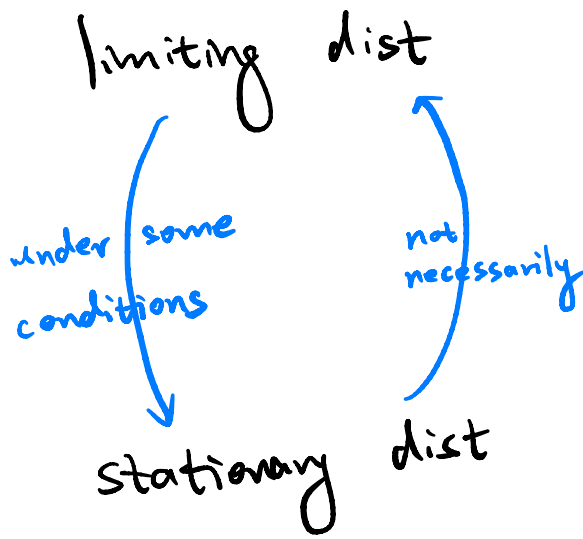
depends on the  
asymptotic behavior  
of  $P^n$ .

( $\pi$  is always a column  
vector)

stationary dist:  $\pi^T$  is a stationary  
dist if

$$\left\{ \begin{array}{l} \textcircled{1}: \pi_1 + \pi_2 + \dots + \pi_n = 1, \forall i, \pi_i \geq 0 \\ \textcircled{2}: \pi^T P = \pi^T \end{array} \right.$$

if  $X_n \sim \pi$ , then  $X_{n+1} \sim \pi$



refer to jupyter notebook  
for week 5, I have some  
examples to show the difference  
between those concepts.

e.g:  $\{X_n\}$  MC, state space  $S = \{1, 2, 3\}$ ,

$$P = \begin{pmatrix} \frac{1}{4} & 0 & \frac{3}{4} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{2}{3} & \frac{1}{3} & 0 \end{pmatrix}, \text{ compute stationary dist } \pi.$$

Pf:  $\pi^T \cdot P = \pi^T$  ①: Plug in  $P$ , solve linear system for  $\pi$ .  
②: Interpretation of eigenvector

①:  $(\pi_1, \pi_2, \pi_3) \cdot \begin{pmatrix} \frac{1}{4} & 0 & \frac{3}{4} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{2}{3} & \frac{1}{3} & 0 \end{pmatrix} = (\pi_1, \pi_2, \pi_3)$

$$\begin{cases} \frac{1}{4}\pi_1 + \frac{2}{3}\pi_3 = \pi_1 \\ \frac{1}{2}\pi_2 + \frac{1}{3}\pi_3 = \pi_2 \\ \frac{3}{4}\pi_1 + \frac{1}{2}\pi_2 = \pi_3 \end{cases} \Rightarrow \text{linear system for } \pi_1, \pi_2, \pi_3$$

normalization  $\rightarrow \pi_1 + \pi_2 + \pi_3 = 1$  solve it to get

$$\pi = \begin{pmatrix} \frac{8}{23} \\ \frac{6}{23} \\ \frac{9}{23} \end{pmatrix}$$

$$\textcircled{2}: \pi^T P = \pi^T$$

↓ take transpose

$$(\pi^T P)^T = \underline{P^T \pi = \pi}$$

$\pi$  is the eigenvector of  $P^T$   
correspondent to eigenvalue 1

(e.g:  $Ax = \lambda x, x \neq 0$ )

$$(P^T - I) \cdot \pi = 0$$

↓

$$P = \begin{pmatrix} \frac{1}{4} & 0 & \frac{3}{4} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{2}{3} & \frac{1}{3} & 0 \end{pmatrix}, \quad P^T = \begin{pmatrix} \frac{1}{4} & 0 & \frac{2}{3} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{3}{4} & \frac{1}{2} & 0 \end{pmatrix}$$

$$P^T - I = \begin{pmatrix} -\frac{3}{4} & 0 & \frac{2}{3} \\ 0 & -\frac{1}{2} & \frac{1}{2} \\ \frac{3}{4} & \frac{1}{2} & -1 \end{pmatrix}$$

$\pi$  is in the null space of  $P^T - I$ .

$$\begin{pmatrix} -\frac{1}{3} & 0 & \frac{1}{3} \\ 0 & -\frac{1}{2} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{2} & -1 \end{pmatrix} \xRightarrow[\text{add row 3}]{\substack{\text{row 2} \\ \times (-2)}} \begin{pmatrix} 0 & 0 & -\frac{1}{3} \\ 0 & -1 & -\frac{2}{3} \\ \frac{1}{3} & \frac{1}{2} & -1 \end{pmatrix} \xRightarrow[\text{row 1} - (\text{row 2} \times \frac{1}{2})]{\text{row 3} \times \frac{4}{3}}$$

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & -\frac{2}{3} \\ 1 & \frac{2}{3} & -\frac{4}{3} \end{pmatrix}$$

$$\begin{cases} \pi_2 - \frac{2}{3}\pi_3 = 0 \\ \pi_1 + \frac{2}{3}\pi_2 - \frac{4}{3}\pi_3 = 0 \end{cases}$$

null space is

$$\begin{pmatrix} \frac{8}{9}a \\ \frac{2}{3}a \\ a \end{pmatrix}$$

Normalization step

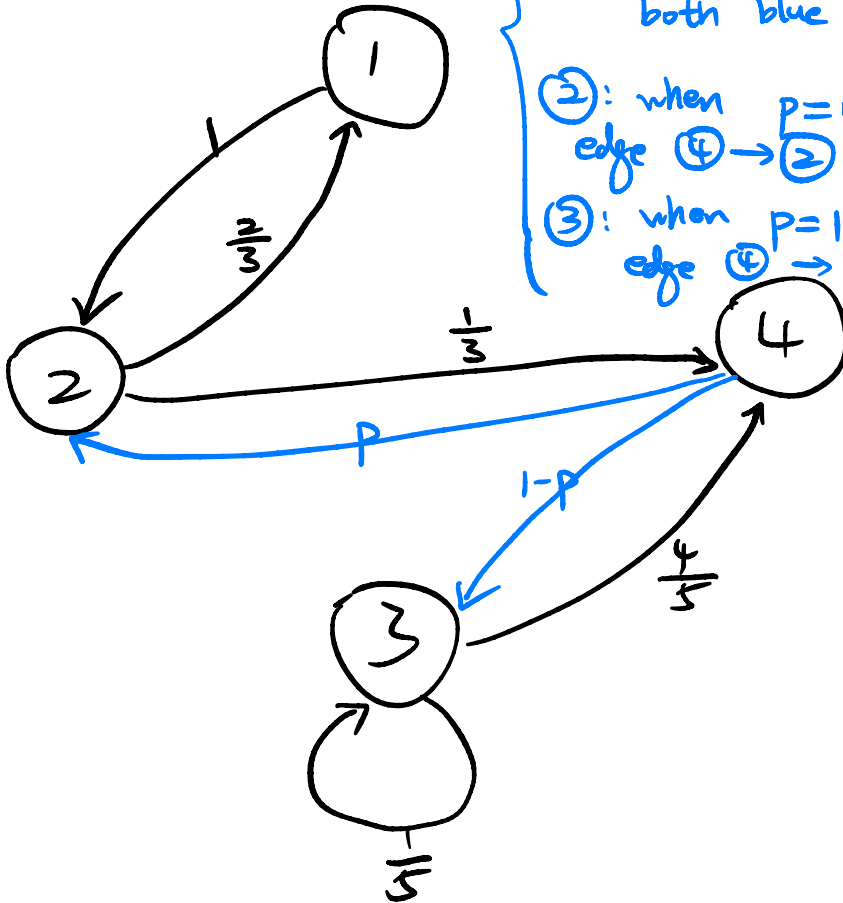
$$\frac{8}{9}a + \frac{2}{3}a + a = 1 \quad (\pi \text{ prob dist})$$

$$\Rightarrow a = \frac{9}{23} \Rightarrow \pi = \begin{pmatrix} \frac{8}{23} \\ \frac{6}{23} \\ \frac{9}{23} \end{pmatrix} \quad \text{same answer.}$$

e.g.:  $\{X_n\}$  MC, state space  $S = \{1, 2, 3, 4\}$ ,

$$P = \begin{pmatrix} 0 & 1 & 0 & 0 \\ \frac{2}{3} & 0 & 0 & \frac{1}{3} \\ 0 & 0 & \frac{1}{5} & \frac{4}{5} \\ 0 & p & 1-p & 0 \end{pmatrix}, \quad p \in [0, 1]$$

(a): Provide transition graph.



①: when  $p \in (0, 1)$ ,  
both blue edges appear.

②: when  $p = 0$  the  
edge  $4 \rightarrow 2$  not exist.

③: when  $p = 1$  the  
edge  $4 \rightarrow 3$  not exist.

(b): Determine all communication classes, which classes are closed?

for any two states in the same comm class, they can reach each other.  
a comm class is closed if  $\forall$  state in the comm class, it can never reach states out of the comm class.

pf: If  $p \in (0, 1)$ , since every two states can reach each other, com class is

$\{1, 2, 3, 4\}$ , closed.

If  $p = 0$ , two comm class  $\{1, 2\}$  and  $\{3, 4\}$ .  $\leftarrow$  closed

$\uparrow$   
not closed  
(since 2 can reach 4)

If  $p = 1$ , two comm class  $\{1, 2, 4\}$  and  $\{3\}$ .

$\uparrow$   
closed

$\uparrow$   
not closed

(since 3 can reach 4)

(c): Now fix  $p=0$ . Initial dist is  $\alpha^T = (0, 0, \frac{5}{9}, \frac{4}{9})$ , compute dist of  $X_1$ , and dist of  $X_{103}$ .

Pf: Dist of  $X_1$  is  $\alpha^T \cdot P$

$$\underbrace{(0, 0, \frac{5}{9}, \frac{4}{9})}_{\alpha^T} \cdot \begin{pmatrix} 0 & 1 & 0 & 0 \\ \frac{2}{3} & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{5} & \frac{4}{5} \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & \frac{5}{9} & \frac{4}{9} \end{pmatrix}_{\alpha^T}$$

$\Rightarrow \alpha^T$  is the stationary distribution.

Dist of  $X_{103}$  is  $\alpha^T \cdot P^{103}$

$$= (\underbrace{\alpha^T P}_{\alpha^T}) \cdot P^{102} = \alpha^T \cdot P^{102} = \dots = \alpha^T \cdot P$$

$$= \alpha^T = \left( 0 \quad 0 \quad \frac{5}{9} \quad \frac{4}{9} \right).$$